

location identifying the desired characteristics of the filter. The signals may be provided via the communication signal, such as TDMA or EDGE signals, or may be separately transmitted and received. The tuning processor then controls the actuators to alter the filters to the desired frequencies. Multiple frequencies may be easily
5 accommodated as desired.

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~~Brief Description of The Drawing~~
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- 10 Figure 1 is a generalized schematic depiction of a cellular telephone system utilizing the principles of the present invention.
- Figure 2 is a generalized representation of a transceiver and a microwave bandpass filter assembly located in a base station of the system of Figure 1.
- 15 Figure 3 is a more specific, schematic representation of the microwave bandpass filter of Figure 2.
- Figure 4 is a mechanical block diagram of the microwave bandpass filter and details the construction and operation of components to actuate the principles of the invention.

20 **Detailed Description**

In Figures 1 and 2, generalized depictions of a cellular telephone system 10 are shown that utilize the principles of the present invention. The system 10 includes numerous cells 12 each of which is serviced by one or more base stations 14. There are numerous ways in which the cells 12, which are usually considered to be circular or
25 hexagonal in shape, may be defined and located relative to each other. Typically, each base station 14 is located at the center of its cell 12 and contains multiple transceivers 16 capable of transmitting signals to and receiving signals from subscribers' telephones, personal computers and laptop computers ("units") 17, 18 and 19 that are located within, and more or less randomly scattered about, the cells 12. These communications

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between the transceivers 16 and the units 17-19 are carried out via self-contained unit antennae (not shown) and antennae 22 associated with the transceivers 16 in the base station 14 of each cell 12 and co-located therewith.

5 The units 17-19 may be stationary wireless units such as a stationary wireless telephone (not shown), a desk top personal computer 18 or stationary laptop computer 17, or may be mobile, such as an automobile phone or wireless telephone 19 or moving laptop computer 17. The latter units 17 and 19, of course, have the capability of wandering in and out of their "home" cell 12 and into and out of other "visited" cells 12 of the system 10. A mobile unit 17 and 19 can also wander into and out of its "home" system 10 and into another "visited" system similar to system 10. This wandering is termed "roaming." Various communication and billing methodologies related to the effectuation and implementation of roaming are known.

15 Each system 10 may also include various switching facilities that effect the connection of the system 10 to foreign systems, such as the wire-connected or Public Switched Telephone Network ("PSTN"), other cellular systems, and satellite transceiving stations. In further embodiments, adjuncts to system 10 include a home office or headquarters, service centers, and/or buildings housing the switching facilities. These adjuncts, while populated with employees and contractors of the owner/operator of system 10, are remote from most of the base stations 14.

20 Typically, units 17-19 and the transceivers 16 of the system 10, have utilized a single communication protocol, such as AMPS/TDMA (30 kHz) or EDGE (200 kHz). There is increasing momentum to enable cellular systems 10 to simultaneously utilize two or more protocols. Implementing the foregoing presents problems arising from the fact that most of the base stations 14 are usually unmanned and are usually remote from
25 the majority of the system's manned sites, such as its general offices, service centers, and switching centers. Specifically, although manual techniques are known for simultaneously utilizing microwave signals having different bandwidths and center frequencies, manual techniques utilized on the site of a base station 14 would prove

unsatisfactory, as they would require the presence of personnel at the preferably unattended base stations 14.

One technique for permitting one or more transceivers 16 at a base station 14 to simultaneously utilize AMPS/TDMA and EDGE is generally illustrated in Figure 2.

5 Resonant cavity coupling loop adjustment, and its effect on bandpass cavity characteristics, are controlled via remote activation. Base station 14 comprises eight transceiver modules in one embodiment which are coupled to corresponding RF power amplifiers 42. Each power amplifier is coupled to an autotune combiner network 46 having selective microwave bandpass per cavity filter 44. Further detail of a combiner network is shown in Figure 3 and 4. The combiner network 46 is coupled to a further frequency specific passive bandpass filter 49, which in turn is coupled to transmit antenna 22. Lightning protection is coupled to both sides of the bandpass filter 49 as indicated at 50.

15 The cavities in the combiner network 46 work independently of each other, but are combined through a phasing network to provide a single output point for transmission of multiple signals. The purpose of the cavity is to provide a resonant bandpass of a specific frequency, either 30 kHz or 200 kHz. The characteristic of a resonance also provides a significant amount of rejection from the other cavities, usually in the order of 30 to 40 dB. To alter the bandpass characteristics, the Q of the cavity is changed. The cavity Q is defined as the quality factor and is sometimes stated as the ratio of the energy stored to energy lost. The bandwidth of a resonant circuit in terms of Q is: $BW = f_r / Q$, where BW is bandwidth, and f_r is frequency. The Q value defines the selectivity of the cavity and these bandpass characteristics.

25 In Figure 3, the combiner network 46 is shown in further detail. A tuning processor 60 is coupled to a stepper motor 62 to provide movement to alter the size of the resonant cavity of the bandpass cavity filter 44. The tuning processor is also coupled to other elements in Figure 3 as needed to provide control. Such connections are known in the art and are not shown herein to avoid obscuring the invention. A tuning housing 63 and tuning actuator 64 operate to provide changes to the length of a

telescoping neck to adjust insertion loss. Sensors and a feedback loop 66 provide for fine tuning of the characteristics of the housing. A coupler 68 is used to adjust to changing Q caused by the change in size of the resonant cavity.

In operation, a signal processor 70 is controlled by an operator to reconfigure the
5 number of bandpass cavity filters 44 devoted to each protocol. Each cavity filter 44 has two settings of selected resonant cavity parameters, one for each of the protocols. More settings to accommodate more protocols may also be provided. The signal processor 70 provides control signals through the TDMA or EDGE signals at 108, which are
10 processed by tuning processor 60 to provide appropriate signals to stepper motor 62 and tuning housing mechanism 63 to appropriately change selected bandpass filters to accommodate the desired mix of protocols.

Further detail of the bandpass filters 44 is shown in Figure 4. Stepper motor 62 is coupled to a tuning plate 104 to provide adjustment thereof under control of the tuning processor 60. The adjustment is shown by double arrow 106 as a lateral motion
15 further into or out of the tuning cavity 102 to modify the cavity size. Size alteration provides a minimal amount of change to the Q of the filter and provides sufficient altering of the bandwidth and frequency. Stepper motor 62 drives the internal plate 104 that modifies the cavity size. In conjunction, the coupling tuner 68 is turned to adjust to the resulting change in Q in the cavity 102. The motion is provided by connecting
20 member 110, which is coupled between the stepper motor 62 and tuning plate 104. Other types of actuators/motors may be used that provide similar longitudinal motion of the plate 104.

Tuning actuator 64 is shown disposed in a telescoping tuning housing 118 to move a tuning actuator 64 laterally within the housing to adjust the length in order to be
25 optimum for frequency specific requirements. This motion is provided by tuning actuator or motor 114 via axel 116. Motor 114 serves a dual purpose in one embodiment by disengaging from the telescoping neck and driving tuning actuator 64 for fine tuning purposes in the frequency band of interest. These movements provide alteration to the internal structure of the filter, which changes the bandwidth and

frequency of operation. With the use of stepper motors, remote tuning and stabilization is achieved. With coupling and sensors through feedback loop 66, changes due to temperature and vibration within the cavity are changed to offer maximum propagation of the signal.

5 In one embodiment, all four bandpass filters 44 in an autotune combiner 46 have been set to transmit signals using the AMPS/TDMA protocol. The output from the antenna 22 will then comprise 100% AMPS/TDMA, which all of the filters 44 will pass, and 0% of EDGE which none of the filters will pass. If one of the filters 44 is set to pass EDGE and the other three filters pass AMPS/TDMA, the signals emitted by the
10 antenna 22 will be 75% AMPS/TDMA and 25% EDGE. If there is enough demand for the use of signals using the EDGE protocol, a second filter may be adjusted to pass EDGE signals, making the ration 50%/50% or 1:1.

 The necessary adjustments to the filters 44 are preferably made from a location remote from the base station 10. For example, the system operator may utilize a wire,
15 radio or other link between stepping motors 62 which operate tuning actuator 64 and mechanisms 110 that adjust the end plate 104 within the cavity 102. The link may render operative or inoperative the power source for the stepping motor 62 or may control its function in any other known manner. This may be achieved by personnel at the remote location sending appropriate signals over the link to operate the stepping
20 motor to achieve a selected position of the end plate and, accordingly, of the cavity Q to pass or not pass the two different signals. While the remote sending of the adjusting signals can be effected manually, it may be preferred to automatically achieve the desired adjustment of the filters 44. Specifically, facilities in the system measure the demand for communication channels using the two protocols. This measurement is
25 used to produce an adjustment signal to the actuators for the stepping motors. Measurement of demand may be continuous or periodic.

Other embodiments will be apparent to those of skill in the art. While stepper motors have been described, other motors and combination of motors and power transfer mechanisms may be used to provide the desired modifications of various cavity

parameters to obtain desired frequencies. Further, more than two frequencies may easily be provided for. While preferred and other embodiments of the present invention are described above, the scope of the present invention shall be determined from the following claims.

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